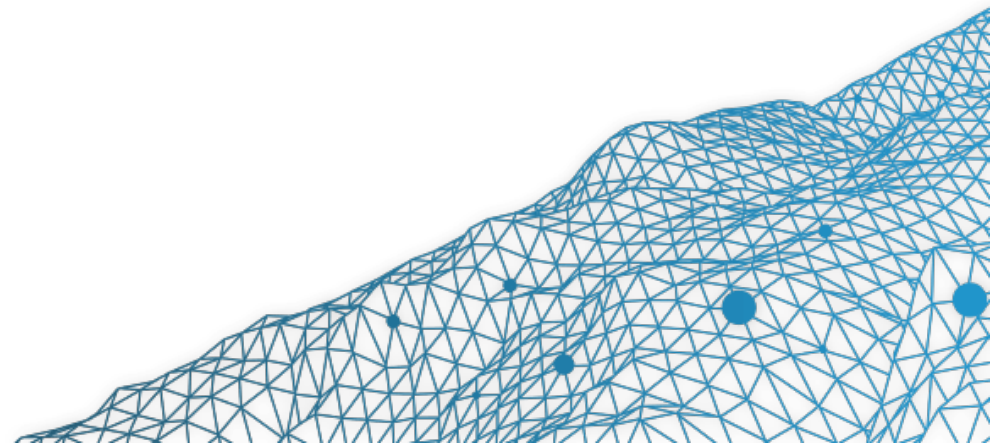


Advanced Econometrics #2: Simulations & Bootstrap

A. Charpentier (Université de Rennes 1)

Université de Rennes 1,
Graduate Course, 2017.



Motivation

Before computers, statistical analysis used probability theory to derive statistical expression for standard errors (or confidence intervals) and testing procedures, for some linear model

$$y_i = \mathbf{x}_i^\top \boldsymbol{\beta} + \varepsilon_i = \beta_0 + \sum_{j=1}^p \beta_j x_{j,i} + \varepsilon_i.$$

But most formulas are approximations, based on large samples ($n \rightarrow \infty$).

With computers, simulations and resampling methods can be used to produce (numerical) standard errors and testing procedure (without the use of formulas, but with a simple algorithm).

Overview

Linear Regression Model: $y_i = \beta_0 + \mathbf{x}_i^\top \boldsymbol{\beta} + \varepsilon_i = \beta_0 + \beta_1 x_{1,i} + \beta_2 x_{2,i} + \varepsilon_i$

- Nonlinear Transformations : smoothing techniques
- Asymptotics vs. Finite Distance : bootstrap techniques
- Penalization : Parcimony, Complexity and Overfit
- From least squares to other regressions : quantiles, expectiles, etc.

Historical References

Permutation methods go back to Fisher (1935) *The Design of Experiments* and Pitman (1937) *Significance tests which may be applied to samples from any population*

(there are $n!$ distinct permutations)

Jackknife was introduced in Quenouille (1949) *Approximate tests of correlation in time series*, popularized by Tukey (1958) *Bias and confidence in not quite large samples*

Bootstrapping started with Monte Carlo algorithms in the 40's, see e.g. Simon & Burstein (1969) *Basic Research Methods in Social Science*

Efron (1979) *Bootstrap methods: Another look at the jackknife* defined a resampling procedure that was coined as “**bootstrap**”.

(there are n^n possible distinct ordered bootstrap samples)

References

Motivation

Bertrand, M., Duflo, E. & Mullainathan, 2004. [Should we trust difference-in-difference estimators?](#). QJE.

References

Davison, A.C. & Hinkley, D.V. 1997 [Bootstrap Methods and Their Application](#). CUP.

Efron B. & Tibshirani, R.J. [An Introduction to the Bootstrap](#). CRC Press.

Horowitz, J.L. 1998 [The Bootstrap](#), Handbook of Econometrics, North-Holland.

MacKinnon, J. 2007 [Bootstrap Hypothesis Testing](#), Working Paper.

Bootstrap Techniques (in one slide)

Bootstrapping is an **asymptotic refinement** based on computer based simulations.

Underlying properties: we know when it might work, or not

Idea : $\{(y_i, \mathbf{x}_i)\}$ is obtained from a stochastic model under \mathbb{P}

We want to generate other samples (not more observations) to reduce uncertainty.

Heuristic Intuition for a Simple (Financial) Model

Consider a return stochastic model, $r_t = \mu + \sigma\varepsilon_t$, for $t = 1, 2, \dots, T$, with (ε_t) is i.i.d. $\mathcal{N}(0, 1)$ [Constant Expected Return Model, CER]

$$\hat{\mu} = \frac{1}{T} \sum_{t=1}^T r_t \text{ and } \hat{\sigma}^2 = \frac{1}{T} \sum_{t=1}^T [r_t - \hat{\mu}]^2$$

then (standard errors)

$$\widehat{se}[\hat{\mu}] = \frac{\hat{\sigma}}{\sqrt{T}} \text{ and } \widehat{se}[\hat{\sigma}] = \frac{\hat{\sigma}}{\sqrt{2T}}$$

then (confidence intervals)

$$\mu \in \left[\hat{\mu} \pm 2\widehat{se}[\hat{\mu}] \right] \text{ and } \sigma \in \left[\hat{\sigma} \pm 2\widehat{se}[\hat{\sigma}] \right]$$

What if the quantity of interest, θ , is another quantity, e.g. a Value-at-Risk ?

Heuristic Intuition for a Simple (Financial) Model

One can use nonparametric bootstrap

1. resampling: generate B “bootstrap samples” by resampling with replacement in the original data,

$$\mathbf{r}^{(b)} = \{r_1^{(b)}, \dots, r_T^{(b)}\}, \text{ with } r_t^{(b)} \in \{r_1, \dots, r_T\}.$$

2. For each sample $\mathbf{r}^{(b)}$, compute $\hat{\theta}^{(b)}$
3. Derive the empirical distribution of $\hat{\theta}$ from $\{\hat{\theta}^{(1)}, \dots, \hat{\theta}^{(B)}\}$.
4. Compute any quantity of interest, standard error, quantiles, etc.

E.g. **estimate the bias**

$$\text{bias}[\hat{\theta}] = \underbrace{\frac{1}{B} \sum_{b=1}^B \hat{\theta}^{(b)}}_{\text{bootstrap mean}} - \underbrace{\frac{1}{B} \sum_{b=1}^B \hat{\theta}}_{\text{estimate}}$$

Heuristic Intuition for a Simple (Financial) Model

E.g. estimate the standard error

$$\text{se}[\hat{\theta}] = \sqrt{\frac{1}{B-1} \sum_{b=1}^B \left(\hat{\theta}^{(b)} - \frac{1}{B} \sum_{b=1}^B \hat{\theta}^{(b)} \right)^2}$$

E.g. estimate the confidence interval, if the bootstrap distribution looks Gaussian

$$\theta \in \left[\hat{\theta} \pm 2\text{se}[\hat{\theta}] \right]$$

and if the distribution does not look Gaussian

$$\theta \in \left[q_{\alpha/2}^{(B)}; q_{1-\alpha/2}^{(B)} \right]$$

where $q_{\alpha}^{(B)}$ denote a quantile from $\{\hat{\theta}^{(1)}, \dots, \hat{\theta}^{(B)}\}$.

Monte Carlo Techniques in Statistics

Law of large numbers (---), if $\mathbb{E}[X] = 0$ and $\text{Var}[X] = 1$: $\sqrt{n} \bar{X}_n \xrightarrow{\mathcal{L}} \mathcal{N}(0, 1)$

What if n is small? What is the distribution of \bar{X}_n ?

Example : X such that $2^{-\frac{1}{2}}(X - 1) \sim \chi^2(1)$

Use Monte Carlo Simulation to derive confidence interval for \bar{X}_n (—).

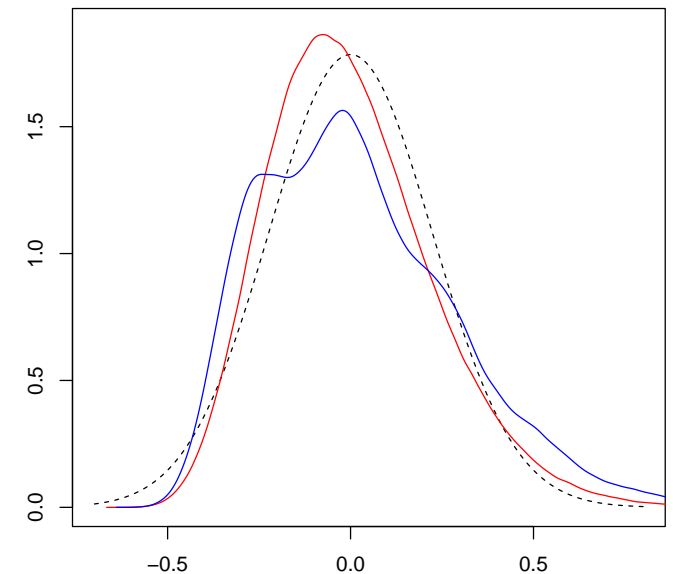
Generate samples $\{x_1^{(m)}, \dots, x_n^{(m)}\}$ from $\chi^2(1)$, and compute $\bar{x}_n^{(m)}$

Then estimate the density of $\{\bar{x}_n^{(1)}, \dots, \bar{x}_n^{(m)}\}$, quantiles, etc.

Problem : need to know the true distribution of X .

What if we have only $\{x_1, \dots, x_n\}$?

Generate samples $\{x_1^{(m)}, \dots, x_n^{(m)}\}$ from \hat{F}_n , and compute $\bar{x}_n^{(m)}$ (—)



Monte Carlo Techniques in Statistics

Consider empirical residuals from a linear regression, $\hat{\varepsilon}_i = y_i - \mathbf{x}_i^\top \hat{\boldsymbol{\beta}}$.

Let $\hat{F}(z) = \frac{1}{n} \sum_{i=1}^n \mathbf{1} \left(\frac{\hat{\varepsilon}_i}{\hat{\sigma}} \leq z \right)$ denote the empirical distribution of Studentized residuals.

Could we test $H_0 : F = \mathcal{N}(0, 1)$?

```
1 > X <- rnorm(50)
2 > cdf <- function(z) mean(X <= z)
```

Simulate samples from a $\mathcal{N}(0, 1)$ (true distribution under H_0)

Quantifying Bias

Consider X with mean $\mu = \mathbb{E}(X)$. Let $\theta = \exp[\mu]$, then $\hat{\theta} = \exp[\bar{x}]$ is a biased estimator of θ , see Horowitz (1998) **The Bootstrap**

Idea 1 : Delta Method, i.e. if $\sqrt{n}[\hat{\tau}_n - \tau] \xrightarrow{\mathcal{L}} \mathcal{N}(0, \sigma^2)$, then, if $g'(\tau)$ exists and is non-null,

$$\sqrt{n}[g(\hat{\tau}_n) - g(\tau)] \xrightarrow{\mathcal{L}} \mathcal{N}(0, \sigma^2 [g'(\tau)]^2)$$

so $\hat{\theta}_1 = \exp[\bar{x}]$ is asymptotically unbiased.

Idea 2 : Delta Method based correction,

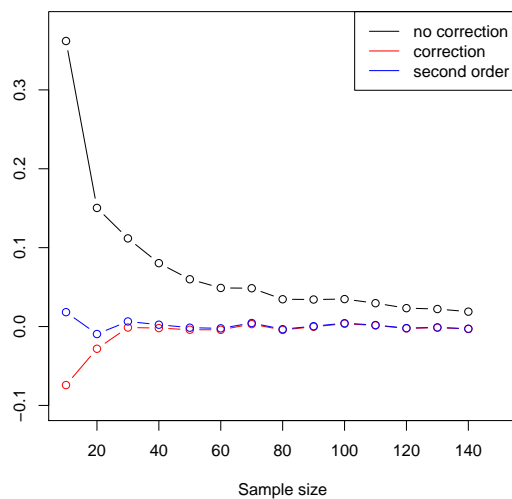
based on $\hat{\theta}_2 = \exp\left[\bar{x} - \frac{s^2}{2n}\right]$ where $s^2 = \frac{1}{n} \sum_{i=1}^n [x_i - \bar{x}]^2$.

Idea 3 : Use Bootstrap, $\hat{\theta}_3 = \frac{1}{B} \sum_{b=1}^n \exp[\bar{x}^{(b)}]$

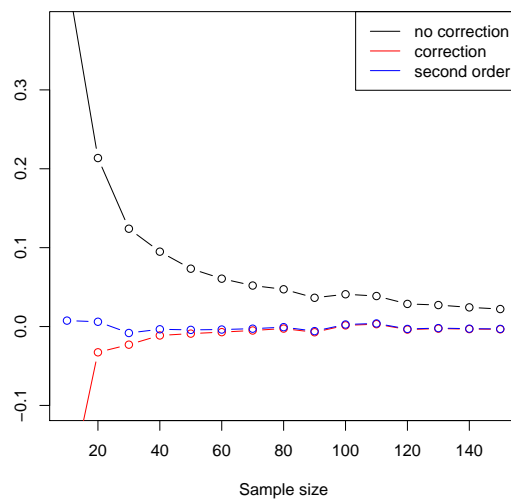
Quantifying Bias

X with mean $\mu = \mathbb{E}(X)$. Let $\theta = \exp[\mu]$. Consider three distributions

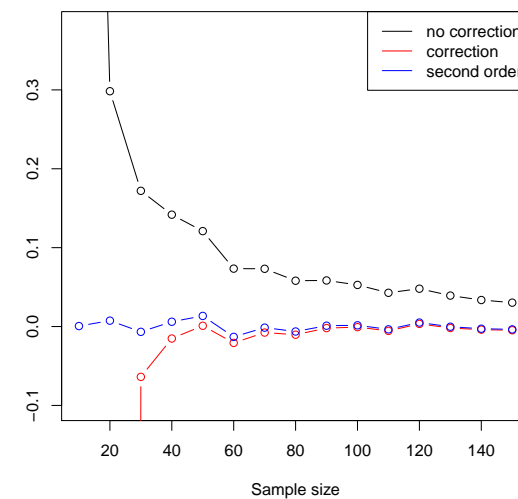
Log-normal



Student t_{10}



Student t_5



Linear Regression & Bootstrap : Parametric

1. sample $\tilde{\varepsilon}_1^{(s)}, \dots, \tilde{\varepsilon}_n^{(s)}$ randomly from $\mathcal{N}(0, \hat{\sigma})$
2. set $y_i^{(s)} = \hat{\beta}_0 + \hat{\beta}_1 x_i + \tilde{\varepsilon}_i^{(s)}$
3. consider dataset $(x_i, y_i^{(b)}) = (x_i, y_i^{(b)})$'s
and fit a linear regression
4. let $\hat{\beta}_0^{(s)}, \hat{\beta}_1^{(s)}$ and $\hat{\sigma}^{2(s)}$ denote the estimated values

Linear Regression & Bootstrap : Residuals

Algorithm 6.1. Davison & Hinkley (1997) **Bootstrap Methods and Applications.**

1. sample $\hat{\varepsilon}_1^{(b)}, \dots, \hat{\varepsilon}_n^{(b)}$ randomly with replacement in $\{\hat{\varepsilon}_1, \hat{\varepsilon}_2, \dots, \hat{\varepsilon}_n\}$
2. set $y_i^{(b)} = \hat{\beta}_0 + \hat{\beta}_1 x_i + \hat{\varepsilon}_i^{(b)}$
3. consider dataset $(x_i, y_i^{(b)}) = (x_i, y_i^{(b)})$'s and fit a linear regression
4. let $\hat{\beta}_0^{(b)}, \hat{\beta}_1^{(b)}$ and $\hat{\sigma}^{2(b)}$ denote estimated values

$$\hat{\beta}_1^{(b)} = \frac{\sum [x_i - \bar{x}] \cdot y_i^{(b)}}{\sum [x_i - \bar{x}]^2} = \hat{\beta}_1 + \frac{\sum [x_i - \bar{x}] \cdot \hat{\varepsilon}_i^{(b)}}{\sum [x_i - \bar{x}]^2}$$

hence $\mathbb{E}[\hat{\beta}_1^{(b)}] = \hat{\beta}_1$, while

$$\text{Var}[\hat{\beta}_1^{(b)}] = \frac{\sum [x_i - \bar{x}]^2 \cdot \text{Var}[\hat{\varepsilon}_i^{(b)}]}{(\sum [x_i - \bar{x}]^2)^2} \sim \frac{\sigma^2}{\sum [x_i - \bar{x}]^2}$$

Linear Regression & Bootstrap : Pairs

Algorithm 6.2. Davison & Hinkley (1997) **Bootstrap Methods and Applications.**

1. sample $\{i_1^{(b)}, \dots, i_n^{(b)}\}$ randomly with replacement in $\{1, 2, \dots, n\}$
2. consider dataset $(x_i^{(b)}, y_i^{(b)}) = (x_{i_i^{(b)}}, y_{i_i^{(b)}})$'s and fit a linear regression
3. let $\widehat{\beta}_0^{(b)}, \widehat{\beta}_1^{(b)}$ and $\widehat{\sigma}^{2(b)}$ denote the estimated values

Remark $\mathbb{P}(i \notin \{i_1^{(b)}, \dots, i_n^{(b)}\}) = \left(1 - \frac{1}{n}\right)^n \sim e^{-1}$

Key issue : residuals have to be **independent** and **identically distributed**

Linear Regression & Bootstrap

Difference between the two algorithms:

- 1) with the second method, we make no assumption about variance homogeneity
potentially more robust to heteroscedasticity
- 2) the simulated samples have different designs, because the x values are randomly sampled

Key issue : residuals have to be **independent** and **identically distributed**

See discussion below on

- dynamic regression, $y_t = \beta_0 + \beta_1 x_t + \beta_2 y_{t-1} + \varepsilon_t$
- heteroskedasticity, $y_i = \beta_0 + \beta_1 x_i + |x_i \cdot \varepsilon_t$
- instrumental variables and two-stage least squares

Monte Carlo Techniques to Compute Integrals

Monte Carlo is a very general technique, that can be used to compute any integral.

Let $X \sim \text{Cauchy}$ what is $\mathbb{P}[X > 2]$. Observe that

$$\mathbb{P}[X > 2] = \int_2^{\infty} \frac{dx}{\pi(1+x^2)} \quad (\sim 0.15)$$

since $f(x) = \frac{1}{\pi(1+x^2)}$ and $Q(u) = F^{-1}(u) = \tan\left(\pi\left[u - \frac{1}{2}\right]\right)$.

Crude Monte Carlo: use the law of large numbers

$$\hat{p}_1 = \frac{1}{n} \sum_{i=1}^n \mathbf{1}(Q(u_i) > 2)$$

where u_i are obtained from i.i.d. $\mathcal{U}([0, 1])$ variables.

Observe that $\text{Var}[\hat{p}_1] \sim \frac{0.127}{n}$.

Crude Monte Carlo (with symmetry): $\mathbb{P}[X > 2] = \mathbb{P}[|X| > 2]/2$ and use the law of large numbers

$$\hat{p}_2 = \frac{1}{2n} \sum_{i=1}^n \mathbf{1}(|Q(u_i)| > 2)$$

where u_i are obtained from i.i.d. $\mathcal{U}([0, 1])$ variables.

Observe that $\text{Var}[\hat{p}_2] \sim \frac{0.052}{n}$.

Using integral symmetries :

$$\int_2^{\infty} \frac{dx}{\pi(1+x^2)} = \frac{1}{2} - \int_0^2 \frac{dx}{\pi(1+x^2)}$$

where the later integral is $\mathbb{E}[h(2U)]$ where $h(x) = \frac{2}{\pi(1+x^2)}$.

From the law of large numbers

$$\hat{p}_3 = \frac{1}{2} - \frac{1}{n} \sum_{i=1}^n h(2u_i)$$

where u_i are obtained from i.i.d. $\mathcal{U}([0, 1])$ variables.

Observe that $\text{Var}[\hat{p}_3] \sim \frac{0.0285}{n}$.

Using integral transformations :

$$\int_2^{\infty} \frac{dx}{\pi(1+x^2)} = \int_0^{1/2} \frac{y^{-2}dy}{\pi(1-y^{-2})}$$

which is $\mathbb{E}[h(U/2)]$ where $h(x) = \frac{1}{2\pi(1+x^2)}$.

From the law of large numbers

$$\hat{p}_4 = \frac{1}{4n} \sum_{i=1}^n h(u_i/2)$$

where u_i are obtained from i.i.d. $\mathcal{U}([0, 1])$ variables.

Observe that $\text{Var}[\hat{p}_4] \sim \frac{0.0009}{n}$.

Simulation in Econometric Models

(almost) all quantities of interest can be written $T(\varepsilon)$ with $\varepsilon \sim F$.

E.g. $\hat{\beta} = \beta + (\mathbf{X}^\top \mathbf{X})^{-1} \mathbf{X}^\top \varepsilon$

We need $\mathbb{E}[T(\varepsilon)] = \int t(\varepsilon) dF(\varepsilon)$

Use simulations, i.e. draw n values $\{\varepsilon_1, \dots, \varepsilon_n\}$ since

$$\mathbb{E} \left[\frac{1}{n} \sum_{i=1}^n T(\varepsilon_i) \right] = \mathbb{E}[T(\varepsilon)] \text{ (unbiased)}$$

$$\frac{1}{n} \sum_{i=1}^n T(\varepsilon_i) \xrightarrow{\mathcal{L}} \mathbb{E}[T(\varepsilon)] \text{ as } n \rightarrow \infty \text{ (consistent)}$$

Generating (Parametric) Distributions

Inverse cdf Technique :

Let $U \sim \mathcal{U}([0, 1])$, then $X = F^{-1}(U) \sim F$.

Proof 1:

$$\mathbb{P}[F^{-1}(U) \leq x] = \mathbb{P}[F \circ F^{-1}(U) \leq F(x)] = \mathbb{P}[U \leq F(x)] = F(x)$$

Proof 2: set $u = F(x)$ or $x = F^{-1}(u)$ (change of variable)

$$\mathbb{E}[h(X)] = \int_{\mathbb{R}} h(x) dF^*(x) = \int_0^1 h(F^{-1}(u)) du = \mathbb{E}[h(F^{-1}(U))]$$

with $U \sim \mathcal{U}([0, 1])$, i.e. $X \stackrel{\mathcal{L}}{=} F^{-1}(U)$.

Rejection Techniques

Problem : If $X \sim F$, how to draw from X^* , i.e. X conditional on $X \in [a, b]$?

Solution : draw X and use **accept-reject** method

1. if $x \in [a, b]$, keep it (accept)
2. if $x \notin [a, b]$, draw another value (reject)

If we generate n values, we accept - on average -
 $[F(b) - F(a)] \cdot n$ draws.

Importance Sampling

Problem : If $X \sim F$, how to draw from X conditional on $X \in [a, b]$?

Solution : rewrite the integral and use **importance sampling** method

The conditional censored distribution X^* is

$$dF^*(x) = \frac{dF(x)}{F(b) - F(a)} \mathbf{1}(x \in [a, b])$$

Alternative for truncated distributions : let $U \sim \mathcal{U}([0, 1])$ and set $\tilde{U} = [1 - U]F(a) + UF(b)$ and $Y = F^{-1}(\tilde{U})$

Going Further : MCMC

Intuition : we want to use the Central Limit Theorem, but i.i.d. sample is a (too) strong assumption: if (X_i) is i.i.d. with distribution F ,

$$\frac{1}{\sqrt{n}} \left(\sum_{i=1}^n h(X_i) - \int h(x) dF(x) \right) \xrightarrow{\mathcal{L}} \mathcal{N}(0, \sigma^2), \text{ as } n \rightarrow \infty.$$

Use the **ergodic theorem**: if (X_i) is a **Markov Chain** with invariant measure μ ,

$$\frac{1}{\sqrt{n}} \left(\sum_{i=1}^n h(X_i) - \int h(x) d\mu(x) \right) \xrightarrow{\mathcal{L}} \mathcal{N}(0, \sigma^2), \text{ as } n \rightarrow \infty.$$

See **Gibbs sampler**

Example : complicated joint distribution, but simple conditional ones

Going Further : MCMC

To generate $\mathbf{X} | \mathbf{X}^\top \mathbf{1} \leq m$ with $\mathbf{X} \sim \mathcal{N}(\mathbf{0}, \mathbb{I})$ (in dimension 2)

1. draw X_1 from $\mathcal{N}(0, 1)$
2. draw U from $\mathcal{U}([0, 1])$ and set $\tilde{U} = U\Phi(m - \epsilon_1)$
3. set $X_2 = \Phi^{-1}(\tilde{U})$

See Geweke (1991) [Efficient Simulation from the Multivariate Normal and Distributions Subject to Linear Constraints](#)

Monte Carlo Techniques in Statistics

Let $\{y_1, \dots, y_n\}$ denote a sample from a collection of n i.i.d. random variables with **true (unknown) distribution** F_0 . This distribution can be approximated by \hat{F}_n .

parametric model : $F_0 \in \mathcal{F} = \{F_\theta; \theta \in \Theta\}$.

nonparametric model : $F_0 \in \mathcal{F} = \{F \text{ is a c.d.f.}\}$

The statistic of interest is $T_n = T_n(y_1, \dots, y_n)$ (see e.g. $T_n = \hat{\beta}_j$).

Let G_n denote the statistics of T_n :

Exact distribution : $G_n(t, F_0) = \mathbb{P}_F(T_n \leq t)$ under F_0

We want to estimate $G_n(\cdot, F_0)$ to get **confidence intervals**, i.e. α -quantiles

$$G_n^{-1}(\alpha, F_0) = \inf \{t; G_n(t, F_0) \geq \alpha\}$$

or **p -values**,

$$p = 1 - G_n(t_n, F_0)$$

Approximation of $G_n(t_n, F_0)$

Two strategies to approximate $G_n(t_n, F_0)$:

1. Use $G_\infty(\cdot, F_0)$, the asymptotic distribution as $n \rightarrow \infty$.
2. Use $G_\infty(\cdot, \hat{F}_n)$

Here \hat{F}_n can be the empirical cdf (nonparametric bootstrap) or $F_{\hat{\theta}}$ (parametric bootstrap).

Approximation of $G_n(t_n, F_0)$: Linear Model

Consider the test of $H_0 : \beta_j = 0$, p -value being $p = 1 - G_n(t_n, F_0)$

- **Linear Model with Normal Errors** $y_i = \mathbf{x}_i^\top \boldsymbol{\beta} + \varepsilon_i$ with $\varepsilon_i \sim \mathcal{N}(0, \sigma^2)$.

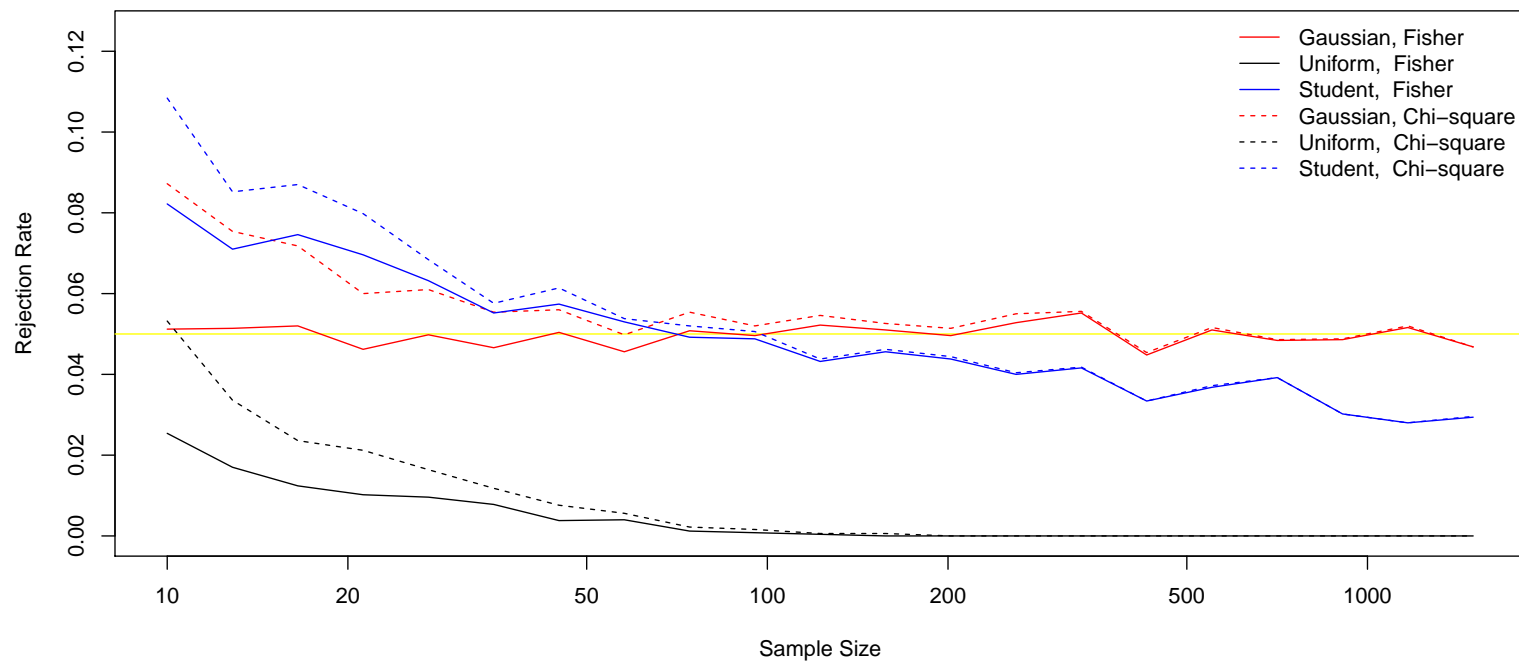
Then $\frac{(\hat{\beta}_j - \beta_j)^2}{\hat{\sigma}_j^2} \sim \mathcal{F}(1, n - k) = G_n(\cdot, F_0)$ where F_0 is $\mathcal{N}(0, \sigma^2)$

- **Linear Model with Non-Normal Errors** $y_i = \mathbf{x}_i^\top \boldsymbol{\beta} + \varepsilon_i$, with $\mathbb{E}[\varepsilon_i] = 0$.

Then $\frac{(\hat{\beta}_j - \beta_j)^2}{\hat{\sigma}_j^2} \xrightarrow{\mathcal{L}} \xi^2(1) = G_\infty(\cdot, F_0)$ as $n \rightarrow \infty$.

Approximation of $G_n(t_n, F_0)$: Linear Model

Application $y_i = \mathbf{x}_i^\top \boldsymbol{\beta} + \varepsilon_i$, $\varepsilon \sim \mathcal{N}(0, 1)$, $\varepsilon \sim \mathcal{U}([-1, +1])$ or $\varepsilon \sim \text{Std}(\nu = 2)$.



Here F_0 is $\mathcal{N}(0, \sigma^2)$

Computation of $G_\infty(t, \hat{F}_n)$

For $b \in \{1, \dots, B\}$, generate bootstrap samples of size n , $\{\hat{\varepsilon}_1^{(b)}, \dots, \hat{\varepsilon}_n^{(b)}\}$ by drawing from \hat{F}_n .

Compute $T^{(b)} = T_n(\hat{\varepsilon}_1^{(b)}, \dots, \hat{\varepsilon}_n^{(b)})$, and use sample $\{T^{(1)}, \dots, T^{(B)}\}$ to compute \hat{G} ,

$$\hat{G}(t) = \frac{1}{B} \sum_{b=1}^B \mathbf{1}(T^{(b)} \leq t)$$

Linear Model: computation of $G_\infty(t, \hat{F}_n)$

Consider the test of $H_0 : \beta_j = 0$, p -value being $p = 1 - G_n(t_n, F_0)$

1. compute $t_n = \frac{(\hat{\beta}_j - \beta_j)^2}{\hat{\sigma}_j^2}$

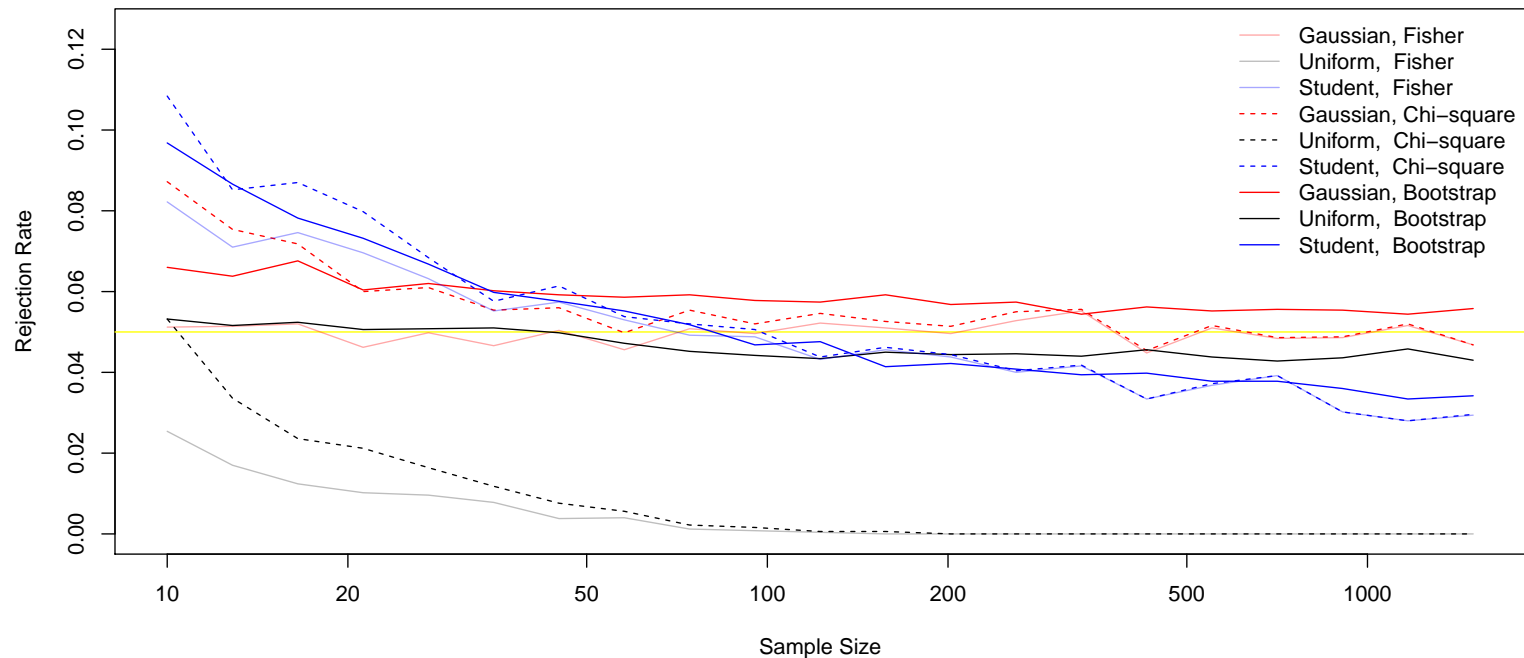
2. generate B bootstrap samples, under the null assumption

3. for each bootstrap sample, compute $t_n^{(b)} = \frac{(\hat{\beta}_j^{(b)} - \hat{\beta}_j)^2}{\hat{\sigma}_j^{2(b)}}$

4. reject H_0 if $\frac{1}{B} \sum_{i=1}^B \mathbf{1}(t_n > t_n^{(b)}) < \alpha$.

Linear Model: computation of $G_\infty(t, \hat{F}_n)$

Application $y_i = \mathbf{x}_i^\top \boldsymbol{\beta} + \varepsilon_i$, $\varepsilon \sim \mathcal{N}(0, 1)$, $\varepsilon \sim \mathcal{U}([-1, +1])$ or $\varepsilon \sim \text{Std}(\nu = 2)$.



Linear Regression

What does **generate B bootstrap samples, under the null assumption** means ?

Use residual bootstrap technique:

Example : (standard) linear model, $y_i = \beta_0 + \beta_1 x_i + \varepsilon_i$ with $H_0 : \beta_1 = 0$.

2.1. Estimate the model under H_0 , i.e. $y_i = \beta_0 + \eta_i$, and save $\{\hat{\eta}_1, \dots, \hat{\eta}_n\}$

2.2. Define $\tilde{\eta} = \{\tilde{\eta}_1, \dots, \tilde{\eta}_n\}$ with $\tilde{\eta} = \sqrt{\frac{n}{n-1}} \hat{\eta}$

2.3. Draw (with replacement) residuals $\tilde{\eta}^{(b)} = \{\tilde{\eta}_1^{(b)}, \dots, \tilde{\eta}_n^{(b)}\}$

2.4. Set $y_i^{(b)} = \hat{\beta}_0 + \tilde{\eta}_i^{(b)}$

2.5. Estimate the regression model $y_i^{(b)} = \beta_0^{(b)} + \beta_1^{(b)} x_i + \varepsilon_i^{(b)}$

Going Further on Linear Regression

Recall that the OLS estimator satisfies

$$\sqrt{n}(\hat{\beta} - \beta_0) = \left(\frac{1}{n} \mathbf{X}^\top \mathbf{X} \right)^{-1} \frac{1}{\sqrt{n}} \sum_{i=1}^n \mathbf{X}_i \varepsilon_i$$

while for the bootstrap

$$\sqrt{n}(\hat{\beta}^{(b)} - \hat{\beta}) = \left(\frac{1}{n} \mathbf{X}^\top \mathbf{X} \right)^{-1} \frac{1}{\sqrt{n}} \sum_{i=1}^n \mathbf{X}_i \varepsilon_i^{(b)}$$

Thus, for i.i.d. data, the variance is

$$\mathbb{E} \left[\left(\frac{1}{\sqrt{n}} \sum_{i=1}^n \mathbf{X}_i \varepsilon_i \right) \left(\frac{1}{\sqrt{n}} \sum_{i=1}^n \mathbf{X}_i \varepsilon_i \right)^\top \right] = \mathbb{E} \left[\frac{1}{n} \sum_{i=1}^n \mathbf{X}_i \mathbf{X}_i^\top \varepsilon_i^2 \right]$$

Going Further on Linear Regression

and similarly (for i.i.d. data)

$$\mathbb{E} \left[\left(\frac{1}{\sqrt{n}} \sum_{i=1}^n \mathbf{X}_i \varepsilon_i^{(b)} \right) \left(\frac{1}{\sqrt{n}} \sum_{i=1}^n \mathbf{X}_i \varepsilon_i^{(b)} \right)^\top \middle| \mathbf{X}, Y \right] = \frac{1}{n} \sum_{i=1}^n \mathbf{X}_i \mathbf{X}_i^\top \widehat{\varepsilon}_i^2$$

Bootstrap with dynamic regression models

Example : linear model, $y_t = \beta_0 + \beta_1 x_t + \beta_2 y_{t-1} + \varepsilon_t$ with $H_0 : \beta_1 = 0$.

2.1. Estimate the model under H_0 , i.e. $y_t = \beta_0 + \beta_2 y_{t-1} + \eta_t$, and save $\{\hat{\eta}_1, \dots, \hat{\eta}_n\}$ (estimated residuals from an AR(1))

2.2. Define $\tilde{\eta} = \{\tilde{\eta}_1, \dots, \tilde{\eta}_n\}$ with $\tilde{\eta} = \sqrt{\frac{n}{n-2}} \hat{\eta}$

2.3. Draw (with replacement) residuals $\tilde{\eta}^{(b)} = \{\tilde{\eta}_1^{(b)}, \dots, \tilde{\eta}_n^{(b)}\}$

2.4. Set (recursively) $y_t^{(b)} = \hat{\beta}_0 + \hat{\beta}_2 y_{t-1}^{(b)} + \tilde{\eta}_t^{(b)}$

2.5. Estimate the regression model $y_t^{(b)} = \beta_0^{(b)} + \beta_1^{(b)} x_t + \beta_2^{(b)} y_{t-1}^{(b)} + \varepsilon_t^{(b)}$

Remark : start (usually) with $y_0^{(b)} = y_1$

Bootstrap with heteroskedasticity

Example : linear model, $y_i = \beta_0 + \beta_1 x_i + |x_i| \cdot \varepsilon_t$ with $H_0 : \beta_1 = 0$.

2.1. Estimate the model under H_0 , i.e. $y_i = \beta_0 + \eta_i$, and save $\{\hat{\eta}_1, \dots, \hat{\eta}_n\}$

2.2. Compute $H_{i,i}$ with $\mathbf{H} = [H_{i,i}]$ from $\mathbf{H} = \mathbf{X}[\mathbf{X}^\top \mathbf{X}]^{-1} \mathbf{X}^\top$.

2.3.a. Define $\tilde{\boldsymbol{\eta}} = \{\tilde{\eta}_1, \dots, \tilde{\eta}_n\}$ with $\tilde{\eta}_i = \pm \frac{\hat{\eta}_i}{\sqrt{1 - H_{i,i}}}$

(here \pm mean $\{-1, +1\}$ with probabilities $\{1/2, 1/2\}$)

2.4.a. Draw (with replacement) residuals $\tilde{\boldsymbol{\eta}}^{(b)} = \{\tilde{\eta}_1^{(b)}, \dots, \tilde{\eta}_n^{(b)}\}$

2.5.a. Set $y_i^{(b)} = \hat{\beta}_0 + \hat{\beta}_2 y_{i-1}^{(b)} + \tilde{\eta}_i^{(b)}$

2.6.a. Estimate the regression model $y_i^{(b)} = \beta_0^{(b)} + \beta_1^{(b)} x_i + \varepsilon_i^{(b)}$

This was suggested in Liu (1988) **Bootstrap procedures under some non - i.i.d. models**

Bootstrap with heteroskedasticity

Example : linear model, $y_i = \beta_0 + \beta_1 x_i + |x_i| \cdot \varepsilon_t$ with $H_0 : \beta_1 = 0$.

2.1. Estimate the model under H_0 , i.e. $y_i = \beta_0 + \eta_i$, and save $\{\hat{\eta}_1, \dots, \hat{\eta}_n\}$

2.2. Compute $H_{i,i}$ with $\mathbf{H} = [H_{i,i}]$ from $\mathbf{H} = \mathbf{X}[\mathbf{X}^\top \mathbf{X}]^{-1} \mathbf{X}^\top$.

2.3.b. Define $\tilde{\boldsymbol{\eta}} = \{\tilde{\eta}_1, \dots, \tilde{\eta}_n\}$ with $\tilde{\eta}_i = \xi_i \frac{\hat{\eta}_i}{\sqrt{1 - H_{i,i}}}$

(here ξ_i takes values $\left\{ \frac{1 - \sqrt{5}}{2}, \frac{1 + \sqrt{5}}{2} \right\}$ with probabilities $\left\{ \frac{\sqrt{5} + 1}{2\sqrt{5}}, \frac{\sqrt{5} - 1}{2\sqrt{5}} \right\}$)

2.4.b. Draw (with replacement) residuals $\tilde{\boldsymbol{\eta}}^{(b)} = \{\tilde{\eta}_1^{(b)}, \dots, \tilde{\eta}_n^{(b)}\}$

2.5.b. Set $y_i^{(b)} = \hat{\beta}_0 + \hat{\beta}_2 y_{i-1}^{(b)} + \tilde{\eta}_i^{(b)}$

2.6.b. Estimate the regression model $y_i^{(b)} = \beta_0^{(b)} + \beta_1^{(b)} x_i + \varepsilon_i^{(b)}$

This was suggested in Mammen (1993) **Bootstrap and wild bootstrap for high dimensional linear models**, ξ_i 's satisfy here $\mathbb{E}[\xi_i^3] = 1$

Bootstrap with heteroskedasticity

Application $y_i = \beta_0 + \beta_1 x_i + |x_i| \cdot \varepsilon_i$, $\varepsilon \sim \mathcal{N}(0, 1)$, $\varepsilon \sim \mathcal{U}([-1, +1])$ or $\varepsilon \sim \text{Std}(\nu = 2)$.

Bootstrap with 2SLS: Wild Bootstrap

Consider a linear model, $y_i = \mathbf{x}_i^\top \boldsymbol{\beta} + \varepsilon_i$ where $\mathbf{x}_i = \mathbf{z}_i^\top \boldsymbol{\gamma} + \mathbf{u}_i$.

Two-stage least squares:

1. regress each column of \mathbf{x} on \mathbf{z} , $\hat{\boldsymbol{\gamma}} = [\mathbf{Z}^\top \mathbf{Z}]^{-1} \mathbf{Z}^\top \mathbf{X}$ and consider the predicted value

$$\hat{\mathbf{X}} = \mathbf{Z} \hat{\boldsymbol{\gamma}} = \underbrace{\mathbf{Z} [\mathbf{Z}^\top \mathbf{Z}]^{-1} \mathbf{Z}^\top}_{\Pi_{\mathbf{Z}}} \mathbf{X}$$

2. regress y on predicted covariates $\hat{\mathbf{X}}$, $y_i = \hat{\mathbf{x}}_i^\top \boldsymbol{\beta} + \varepsilon_i$

Bootstrap with 2SLS: Wild Bootstrap

Example : linear model, $y_i = \beta_0 + \beta_1 x_i + \varepsilon_t$ where $x_i = \mathbf{z}_i^\top \boldsymbol{\gamma} + u_i$ and $\text{Cov}[\varepsilon, u] = \rho$, with $H_0 : \beta_1 = 0$.

So called Wild Bootstrap, see Davidson & Mackinnon (2009) **Wild bootstrap tests for IV regression**

2.1. Estimate the model under H_0 , i.e. $y_i = \beta_0 + \eta_i$, by 2SLS and save $\hat{\mathbf{u}} = \{\hat{\eta}_1, \dots, \hat{\eta}_n\}$

2.2. Estimate $\boldsymbol{\gamma}$ from $x_i = \mathbf{z}_i^\top \boldsymbol{\gamma} + \delta \hat{\eta}_i + u_i$

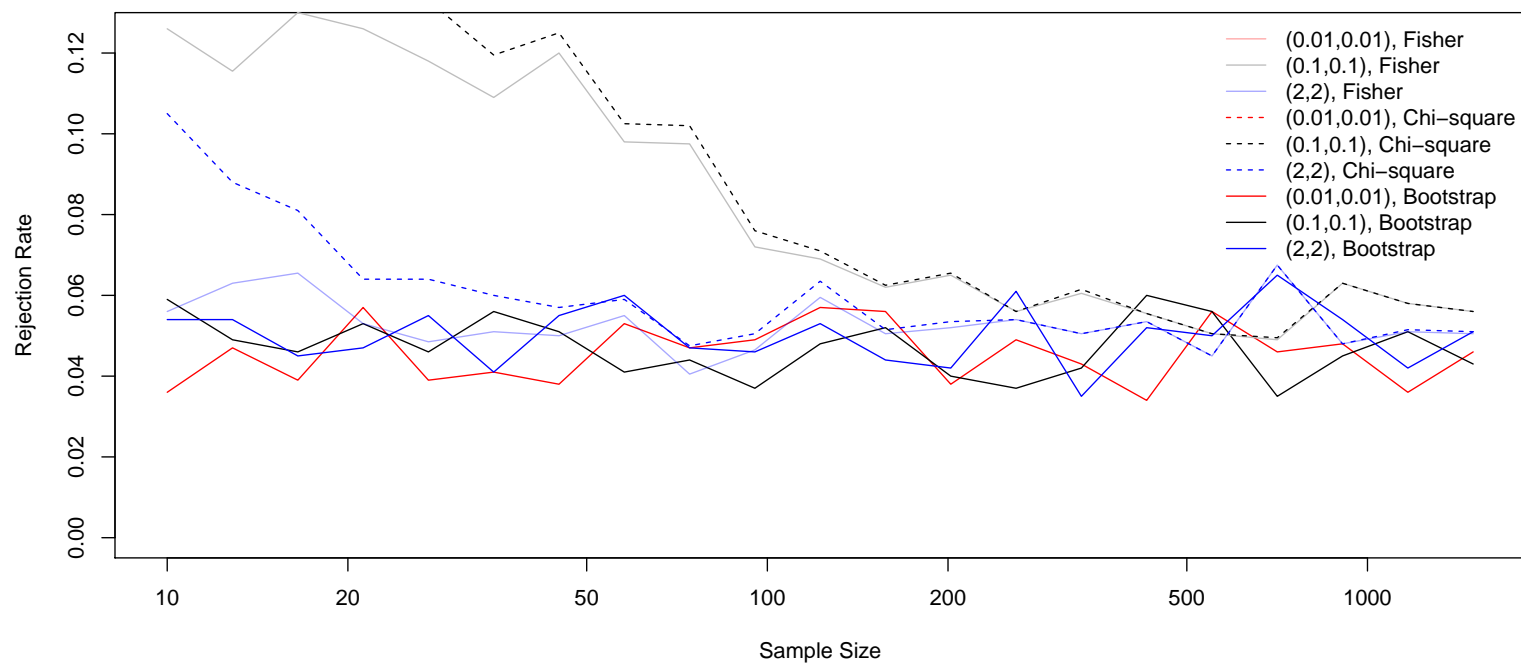
2.3. Define $\tilde{\mathbf{u}} = \{\tilde{u}_1, \dots, \tilde{u}_n\}$ with $\tilde{u}_i = X_i - \mathbf{z}_i^\top \hat{\boldsymbol{\gamma}}$

2.4. Draw (with replacement) pairs of residuals $(\hat{\boldsymbol{\eta}}^{(b)}, \tilde{\mathbf{u}}^{(b)})$ of $(\hat{\eta}_i^{(b)}, \tilde{u}_i^{(b)})$'s

2.5. Set $x_i^{(b)} = \mathbf{z}_i^\top \hat{\boldsymbol{\gamma}} + \tilde{u}_i^{(b)}$ and $y_i^{(b)} = \hat{\beta}_0 + \hat{\eta}_i^{(b)}$

2.6. Estimate (using 2SLS) the regression model $y_i^{(b)} = \beta_0^{(b)} + \beta_1^{(b)} x_i^{(b)} + \varepsilon_i^{(b)}$, where $x_i^{(b)} = \mathbf{z}_i^\top \boldsymbol{\gamma} + u_i$

Bootstrap with 2SLS: Wild Bootstrap



See example Section 5.2 in Horowitz (1998) [The Bootstrap](#).

Estimation of Various Quantifies of Interest

Consider a quadratic model,

$$y_i = \beta_0 + \beta_1 x_i + \beta_2 x_i^2 + \varepsilon_i$$

The minimum is obtained in $\theta = -\beta_1/2\beta_2$.

What could be the standard error for θ ?

1. Use of the **Delta-Method**

$$\theta = g(\beta_1, \beta_2) = \frac{-\beta_1}{2\beta_2}$$

Since $\frac{\partial \theta}{\partial \beta_1} = \frac{-1}{2\beta_2}$ and $\frac{\partial \theta}{\partial \beta_2} = \frac{\beta_1}{2\beta_2^2}$, the variance is

$$\frac{1}{4} \begin{bmatrix} -1 & \beta_1 \\ 2\beta_2 & 2\beta_2^2 \end{bmatrix} \begin{bmatrix} \sigma_1^2 & \sigma_{12} \\ \sigma_{12} & \sigma_2^2 \end{bmatrix} \begin{bmatrix} -1 & \beta_1 \\ 2\beta_2 & 2\beta_2^2 \end{bmatrix}^T = \frac{\sigma_1^2 \beta_2^2 - 2\beta_1 \beta_2 \sigma_{12} + \beta_1^2 \sigma_2^2}{4\beta_2^2}$$

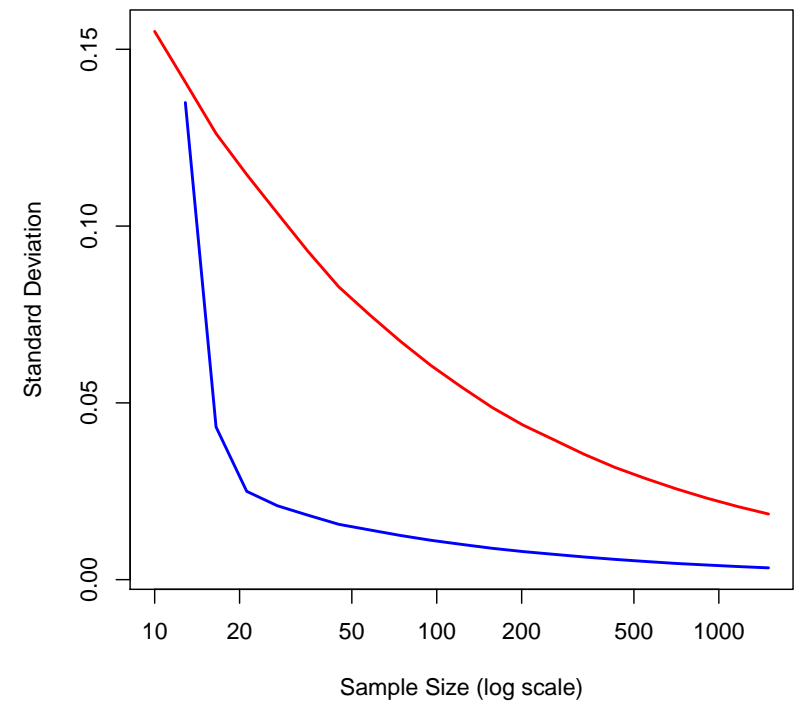
Estimation of Various Quantifies of Interest

2. Use of Bootstrap

standard deviation of $\hat{\theta}$,

— delta method vs.

— bootstrap.



Box-Cox Transform

$$y_\lambda = \beta_0 + \beta_1 x + \varepsilon, \text{ with } y_\lambda = \frac{y^{\lambda-1}}{\lambda}$$

with the limiting case $y_0 = \log[y]$.

We assume that for some (unkown) λ_0 , $\varepsilon \sim \mathcal{N}(0, \sigma^2)$.

As in Horowitz (1998) **The Bootstrap**, use residual bootstrap:

$$y_i^{(b)} = (\lambda[\hat{\beta}_0 + \hat{\beta}_1 x_i + \hat{\varepsilon}^{(b)}])^{1/\lambda}$$

Kernel based Regression

Consider some kernel based regression of estimate $m(x) = \mathbb{E}[Y|X = x]$,

$$\hat{m}_h(x) = \frac{1}{nh\hat{f}_n(x)} \sum_{i=1}^n y_i k\left(\frac{x - x_i}{h}\right) \quad \text{where} \quad \hat{f}_n(x) = \frac{1}{nh} \sum_{i=1}^n k\left(\frac{x - x_i}{h}\right)$$

We have seen that the bias was

$$b_h(x) = \mathbb{E}[\tilde{m}(x)] - m(x) \propto h^2 \left(\frac{1}{2} m''(x) + m'(x) \frac{f'(x)}{f(x)} \right)$$

and the variance

$$v_h(x) \propto \frac{\text{Var}[Y|X = x]}{nhf(x)}$$

Further

$$Z_n(x) = \frac{\hat{m}_{h_n}(x) - m(x) - b_{h_n}(x)}{\sqrt{v_h h_n(x)}} \xrightarrow{\mathcal{L}} \mathcal{N}(0, 1) \text{ as } n \rightarrow \infty.$$

Kernel based Regression

Idea: convert $Z_n(x)$ into an asymptotically pivotal statistic

Observe that

$$\hat{m}_h(x) - m(x) \sim \frac{1}{nh\hat{f}_n(x)} \sum_{i=1}^n [y_i - m(x)] k\left(\frac{x - x_i}{h}\right)$$

so that $v_n(x)$ can be estimated by

$$\hat{v}_n(x) = \frac{1}{(nh\hat{f}_n(x))^2} \sum_{i=1}^n [y_i - \hat{m}_h(x)]^2 k\left(\frac{x - x_i}{h}\right)^2$$

then set

$$\hat{\theta} = \frac{\hat{m}_h(x) - m(x)}{\sqrt{\hat{v}_n(x)}}$$

$\hat{\theta}$ is asymptotically $\mathcal{N}(0, 1)$ and it is an asymptotically pivotal statistic

Poisson Regression

Diagnosis period		Reporting-delay interval (quarters):									Total reports to end of 1992
Year	Quarter	0 [†]	1	2	3	4	5	6	...	≥14	
1988	1	31	80	16	9	3	2	8	...	6	174
	2	26	99	27	9	8	11	3	...	3	211
	3	31	95	35	13	18	4	6	...	3	224
	4	36	77	20	26	11	3	8	...	2	205
1989	1	32	92	32	10	12	19	12	...	2	224
	2	15	92	14	27	22	21	12	...	1	219
	3	34	104	29	31	18	8	6	...		253
	4	38	101	34	18	9	15	6	...		233
1990	1	31	124	47	24	11	15	8	...		281
	2	32	132	36	10	9	7	6	...		245
	3	49	107	51	17	15	8	9	...		260
	4	44	153	41	16	11	6	5	...		285
1991	1	41	137	29	33	7	11	6	...		271
	2	56	124	39	14	12	7	10			263
	3	53	175	35	17	13	11				306
	4	63	135	24	23	12					258
1992	1	71	161	48	25						310
	2	95	178	39							318
	3	76	181								273
	4	67									133

Example : see Davison & Hinkley (1997) *Bootstrap Methods and Applications*, UK AIDS diagnoses, 1988-1992.

Reporting delay can be important

Let j denote **year** and k denote **delay**. Assumption

$$N_{j,k} \sim \mathcal{P}(\lambda_{j,k}) \text{ with } \lambda_{j,k} = \exp[\alpha_j + \beta_k]$$

Unreported diagnoses for period j : $\sum_{k \text{ unobserved}} \lambda_{j,k}$

Prediction : $\sum_{k \text{ unobserved}} \hat{\lambda}_{j,k} = \exp[\hat{\alpha}_j] \sum_{k \text{ unobserved}} \exp[\hat{\beta}_k]$

Poisson regression is a GLM : confidence intervals on coefficients are asymptotic.

Let V denote the variance function, then Pearson residuals are

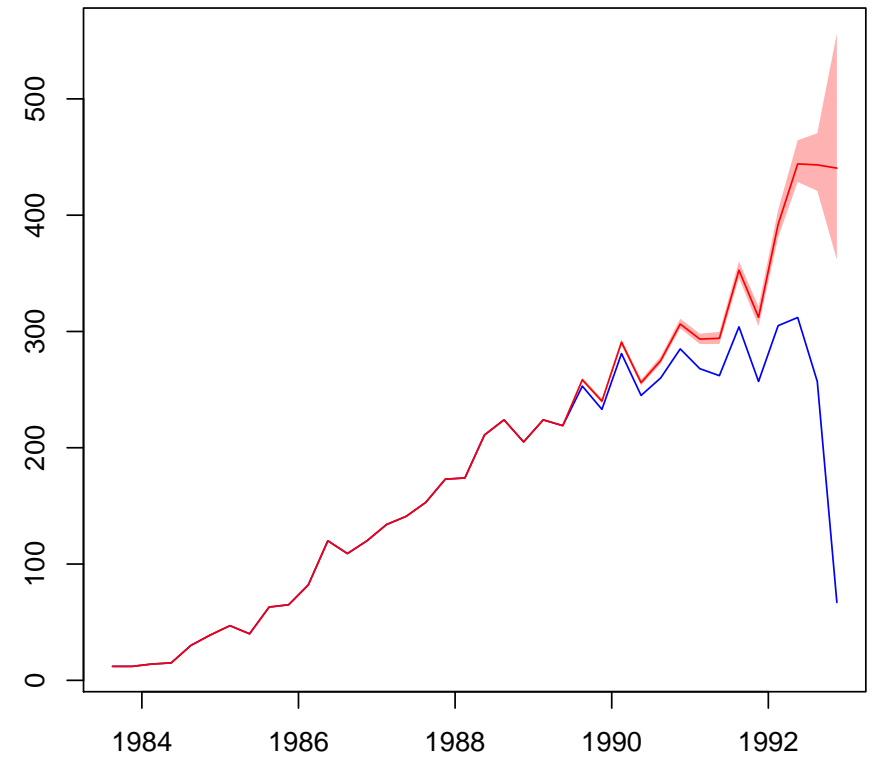
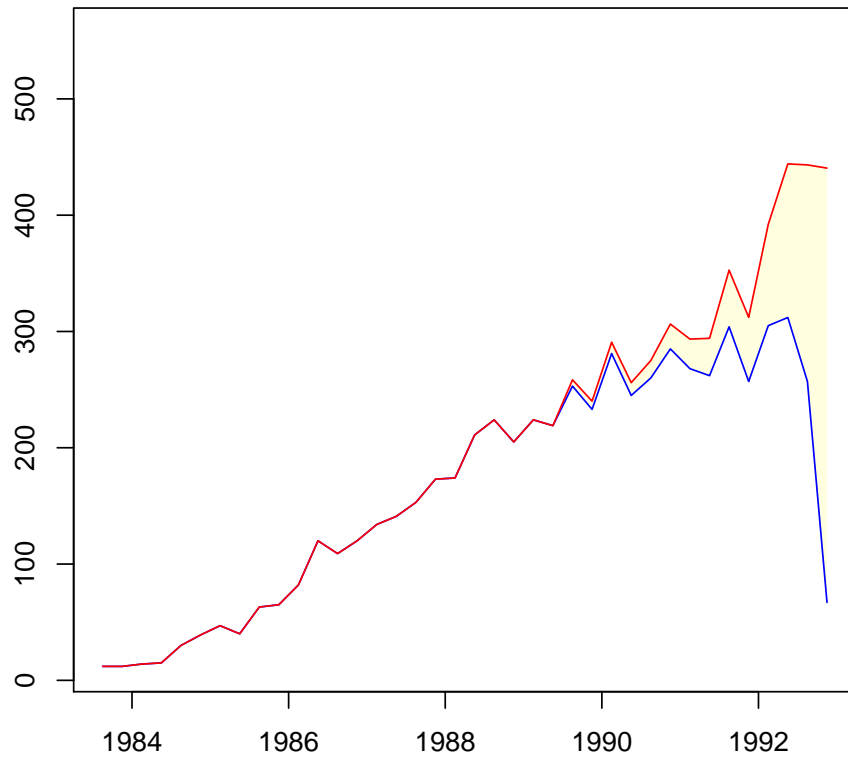
$$\hat{\epsilon}_i = \frac{y_i - \hat{\mu}_i}{\sqrt{V[\hat{\mu}_i]}}$$

so here

$$\hat{\epsilon}_{j,k} = \frac{n_{j,k} - \hat{\lambda}_{j,k}}{\sqrt{\hat{\lambda}_{j,k}}}$$

Poisson Regression

So bootstrapped responses are $n_{j,k}^* = \hat{\lambda}_{j,k} + \sqrt{\hat{\lambda}_{j,k}} \cdot \hat{\epsilon}_{j,k}^*$



Pivotal Case (or not)

In some cases, $G(\cdot, F)$ does not depend on F , $\forall F \in \mathcal{F}$.

Then T_n is said to be **pivotal**, relative to \mathcal{F} .

Example : consider the case of Gaussian residuals, $\mathcal{F} = \mathcal{F}_{\text{gaussian}}$. Then

$$T = \frac{\bar{y} - \mathbb{E}[Y]}{\hat{\sigma}} \sim \text{Std}(n - 1)$$

which does not depend on F (but it does depend on \mathcal{F})

If T_n is not pivotal, it is still possible to look for bounds on $G_n(t, F)$,

$$B_n(t) = \left[\inf_{F \in \mathcal{F}_\star} \{G_n(t, F)\}; \sup_{F \in \mathcal{F}_\star} \{G_n(t, F)\} \right]$$

for instance, when a set of *reasonable values* for \mathcal{F}_\star is provided, by an expert.

Pivotal Case (or not)

$$B_n(t) = \left[\inf_{F \in \mathcal{F}_\star} \{G_n(t, F)\}; \sup_{F \in \mathcal{F}_\star} \{G_n(t, F)\} \right]$$

In the parametric case, set

$$\mathcal{F}_\star = \{F_\theta, \theta \in IC\}$$

where IC is some confidence interval.

In the nonparametric case, use Kolomogorov-Smirnov statistics to get bounds, using quantiles of

$$\sqrt{n} \sup\{|\hat{F}_n(t) - F_0(t)|\}$$

Pivotal Function and Studentized Statistics

It is interesting to **studentize** any statistics.

Let v denote the variance of $\hat{\theta}$ (computed using $\{y_1, \dots, y_n\}$). Then set

$$Z = \frac{\hat{\theta} - \theta}{\sqrt{v}}$$

If quantiles of Z are known (and denoted z_α), then

$$\mathbb{P}\left(\hat{\theta} + \sqrt{v}z_{\alpha/2} \leq \theta \leq \hat{\theta} + \sqrt{v}z_{1-\alpha/2}\right) = 1 - \alpha$$

Idea : use a (double) bootstrap procedure

Pivotal Function and Double Bootstrap Procedure

1. Generate a bootstrap sample $\mathbf{y}^{(b)} = \{y_1^{(b)}, \dots, y_n^{(b)}\}$
2. Compute $\hat{\theta}^{(b)}$
3. From $\mathbf{y}^{(b)}$ generate β bootstrap sample, and compute $\{\hat{\theta}_1^{(b)}, \dots, \hat{\theta}_\beta^{(b)}\}$
4. Compute $\hat{v}^{(b)} = \frac{1}{\beta} \sum_{j=1}^{\beta} (\hat{\theta}_j^{(b)} - \bar{\theta}^{(b)})^2$
5. Set $z^{(b)} = \frac{\hat{\theta}^{(b)} - \hat{\theta}}{\sqrt{\hat{v}^{(b)}}}$

Then use $\{z^{(1)}, \dots, z^{(B)}\}$ to estimate the distribution of z 's (and some quantiles).

$$\mathbb{P}\left(\hat{\theta} + \sqrt{v}z_{\alpha/2}^{(B)} \leq \theta \leq \hat{\theta} + \sqrt{v}z_{1-\alpha/2}^{(B)}\right) = 1 - \alpha$$

Why should we studentize ?

Here $Z \xrightarrow{\mathcal{L}} \mathcal{N}(0, 1)$ as $n \rightarrow \infty$ (CLT). Using Edgeworth series,

$$\mathbb{P}[Z \leq z|F] = \Phi(z) + n^{-1/2}p(z)\varphi(z) + O(n^{-1})$$

for some quadratic polynomial $p(\cdot)$. For $Z^{(b)}$

$$\mathbb{P}[Z^{(b)} \leq z|\hat{F}] = \Phi(z) + n^{-1/2}\hat{p}(z)\varphi(z) + O(n^{-1})$$

where $\hat{p}(z) = p(z) + O(n^{-1/2})$, so

$$\mathbb{P}[Z \leq z|F] - \mathbb{P}[Z^{(b)} \leq z|\hat{F}] = O(n^{-1})$$

But if we do not studentize, $Z = (\hat{\theta} - \theta) \xrightarrow{\mathcal{L}} \mathcal{N}(0, \nu)$ as $n \rightarrow \infty$ (CLT). Using Edgeworth series,

$$\mathbb{P}[Z \leq z|F] = \Phi\left(\frac{z}{\sqrt{\nu}}\right) + n^{-1/2}p'\left(\frac{z}{\sqrt{\nu}}\right)\varphi\left(\frac{z}{\sqrt{\nu}}\right) + O(n^{-1})$$

for some quadratic polynomial $p(\cdot)$. For $Z^{(b)}$

$$\mathbb{P}[Z^{(b)} \leq z | \hat{F}] = \Phi\left(\frac{z}{\sqrt{\hat{\nu}}}\right) + n^{-1/2} \hat{p}'\left(\frac{z}{\sqrt{\hat{\nu}}}\right) \varphi\left(\frac{z}{\sqrt{\hat{\nu}}}\right) + O(n^{-1})$$

recall that $\hat{\nu} = \nu + o(n^{-1/2})$, and thus

$$\mathbb{P}[Z \leq z | F] - \mathbb{P}[Z^{(b)} \leq z | \hat{F}] = O(n^{-1/2})$$

Hence, studentization reduces error, from $O(n^{-1/2})$ to $O(n^{-1})$

Variance estimation

The estimation of $\text{Var}[\hat{\theta}]$ is necessary for studentized bootstrap.

- double bootstrap (used here)
- delta method
- jackknife (leave-one-out)

Double Bootstrap

Requires $B \times \beta$ resamples, e.g. $B \sim 1,000$ while $\beta \sim 100$

Delta Method

Let $\hat{\tau} = g(\hat{\theta})$, with $g'(\theta) \neq 0$.

$$\mathbb{E}[\hat{\tau}] = g(\theta) + O(n^{-1})$$

$$\text{Var}[\hat{\tau}] = \text{Var}[\hat{\theta}]g'(\theta)^2 + O(n^{-3/2})$$

Variance estimation

Idea: find a transformation such that $\text{Var}[\widehat{\tau}]$ is constant. Then

$$\text{Var}[\widehat{\theta}] \sim \frac{\text{Var}[\widehat{\tau}]}{g'(\widehat{\theta})^2}$$

There is also a **nonparametric delta method**, based on the **influence function**.

Influence Function and Taylor Expansion

Taylor expansion

$$t(y) = t(x) + \int_x^y f'(z)cdz \quad t(x) + (y - x)f'(x)$$

$$t(G) = t(F) + \int_{\mathbb{R}} L_t(z, F)dG(z)$$

where L_t is the Fréchet derivative,

$$L_t(z, F) = \left. \frac{\partial[(1 - \epsilon)F + \epsilon\Delta_z]}{\partial\epsilon} \right|_{\epsilon=0}$$

where $\Delta_z(t) = \mathbf{1}(t > z)$ denote the cdf of the Dirac measure in z .

For instance, observe that

$$t(\hat{F}_n) = t(F) + \frac{1}{n} \sum_{i=1}^n L_t(y_i, F)$$

Influence Function and Taylor Expansion

This can be used to estimate the variance. Set

$$V_L = \frac{1}{n^2} \sum_{i=1}^n L(y_i, F)^2$$

where $L(y, F)$ is the influence function for $\theta = t(F)$ for observation at y when distribution is F .

The empirical version is $\ell_i = L(y_i, \hat{F})$ and set

$$\hat{V}_L = \frac{1}{n^2} \sum_{i=1}^n \ell_i^2$$

Example : let $\theta = \mathbb{E}[X]$ with $X \sim F$, then

$$\hat{\theta} = \bar{y}_n = \sum_{i=1}^n \frac{1}{n} y_i = \sum_{i=1}^n \omega_i y_i \text{ where } \omega_i = \frac{1}{n}$$

Influence Function and Taylor Expansion

Change ω 's in direction j :

$$\omega_j = \epsilon + \frac{1 - \epsilon}{n}, \text{ while } \forall i \neq j, \omega_i = \frac{1 - \epsilon}{n},$$

then $\hat{\theta}$ changes in

$$\underbrace{[y_h - \hat{\theta}]}_{\ell_j} \epsilon + \hat{\theta}$$

Hence, ℓ_j is the standardized change in $\hat{\theta}$ with an increase in direction j , and

$$\hat{V}_L = \frac{n-1}{n} \frac{\text{Var}[X]}{n}.$$

Example : consider a ratio, $\theta = \frac{\mathbb{E}[X]}{\mathbb{E}[Y]}$, then

$$\hat{\theta} = \frac{\bar{x}_n}{\bar{y}_n} \text{ and } \ell_j = \frac{x_j - \hat{\theta}y_j}{\bar{y}_n}$$

Influence Function and Taylor Expansion

so that

$$\widehat{V}_L = \frac{1}{n^2} \sum_{i=1}^n \left(\frac{x_j - \widehat{\theta} y_j}{\bar{y}_n} \right)^2$$

Example : consider a correlation coefficient,

$$\theta = \frac{\mathbb{E}[XY] - \mathbb{E}[X] \cdot \mathbb{E}[Y]}{\sqrt{(\mathbb{E}[X^2] - \mathbb{E}[X]^2) \cdot (\mathbb{E}[Y^2] - \mathbb{E}[Y]^2)}}$$

Let $\overline{xy} = n^{-1} \sum x_i y_i$, so that

$$\widehat{\theta} = \frac{\overline{xy} - \bar{x} \cdot \bar{y}}{\sqrt{(\overline{x^2} - \bar{x}^2) \cdot (\overline{y^2} - \bar{y}^2)}}$$

Jackknife

An approximation of l_i is $l_i^* = (n-1)(\hat{\theta} - \hat{\theta}_{(-j)})$ where $\hat{\theta}_{(-j)}$ is the statistics computed from sample $\{y_1, \dots, y_{i-1}, y_{i+1}, \dots, y_n\}$

One can define **Jackknife bias** and **Jackknife variance**

$$b^* = \frac{-1}{n} \sum_{i=1}^n l_i^* \quad \text{and} \quad v^* = \frac{1}{n(n-1)} \left(\sum_{i=1}^n l_i^{*2} - nb^{*2} \right)$$

cf numerical differentiation when $\epsilon = -\frac{1}{(n-1)}$.

Convergence

Given a sample $\{y_1, \dots, y_n\}$, i.i.d. with distribution F , set

$$\hat{F}_n(t) = \frac{1}{n} \sum_{i=1}^n \mathbf{1}(y_i \leq t)$$

Then

$$\sup \{|\hat{F}_n(t) - F_0(t)|\} \xrightarrow{\mathbb{P}} 0, \text{ as } n \rightarrow \infty.$$

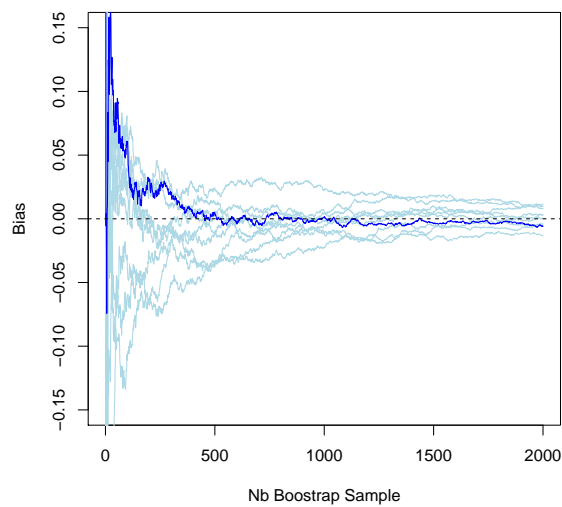
How many Bootstrap Samples?

Easy to take $B \geq 5000$

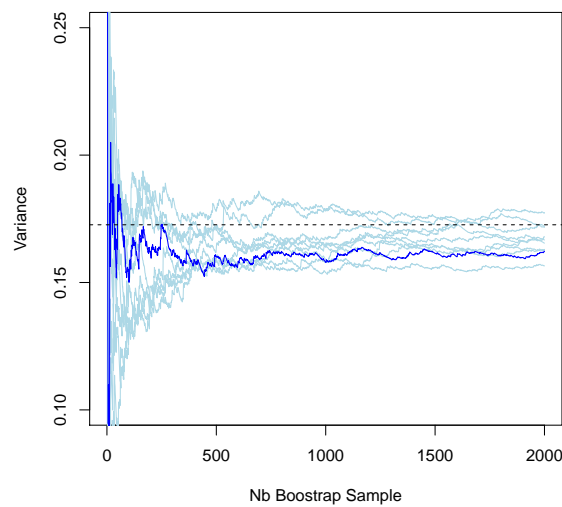
$R > 100$ to estimate bias or variance

$R > 1000$ to estimate quantiles

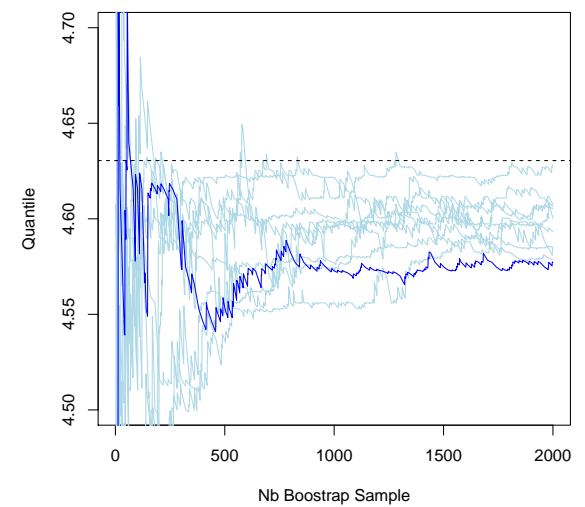
Bias



Variance



Quantile



Consistency

We expect something like

$$G_n(t, \hat{F}_n) \sim G_\infty(t, \hat{F}_n) \sim G_\infty(t, F_0) \sim G_n(t, F_0)$$

$G_n(t, \hat{F}_n)$ is said to be consistent if under each $F_0 \in \mathcal{F}$,

$$\sup_t \mathbb{P}\{|G_n(t, \hat{F}_n) - G_\infty(t, F_0)|\} \xrightarrow{\mathbb{P}} 0$$

Example: let $\theta = \mathbb{E}_{F_0}(X)$ and consider $T_n = \sqrt{n}(\bar{X} - \theta)$. Here

$$G_n(t, F_0) = \mathbb{P}_{F_0}(T_n \leq t)$$

Based on bootstrap samples, a bootstrap version of T_n is

$$T_n^{(b)} = \sqrt{n}(\bar{X}^{(b)} - \bar{X}) \text{ since } \bar{X} = \mathbb{E}_{\hat{F}_n}(X)$$

and $G_n(t, \hat{F}_n) = \mathbb{P}_{\hat{F}_n}(T_n \leq t)$

Consistency

Consider a regression model $y_i = \mathbf{x}_i^\top \boldsymbol{\beta} + \varepsilon_i$

The natural assumption is $\mathbb{E}[\varepsilon_i | \mathbf{X}] = 0$ with ε_i 's i.i.d. $\sim F$.

The parameter of interest is $\theta = \beta_j$, and let $\hat{\beta}_j = \theta(\hat{F}_n)$.

1. The statistics of interest is $T_n = \sqrt{n}[\hat{\beta}_j - \beta_j]$.

We want to know $G_n(t, F_0) = \mathbb{P}_{F_0}(T_n \leq t)$.

Let $\mathbf{x}^{(b)}$ denote a bootstrap sample.

Compute $T_n^{(b)} = \sqrt{n}(\hat{\beta}_j^{(b)} - \hat{\beta}_j)$, and then

$$G_n(t, F_n) = \frac{1}{B} \sum_{b=1}^B \mathbf{1}(T_n^{(b)} \leq t)$$

Consistency

2. The statistics of interest is $T_n = \sqrt{n} \frac{[\hat{\beta}_j - \beta_j]}{\sqrt{\text{Var}[\hat{\beta}_j]}}$.

We want to know $G_n(t, F_0) = \mathbb{P}_{F_0}(T_n \leq t)$.

Let $\mathbf{x}^{(b)}$ denote a bootstrap sample.

Compute $T_n^{(b)} = \sqrt{n} \frac{[\hat{\beta}_j^{(b)} - \hat{\beta}_j]}{\sqrt{\text{Var}^{(b)}[\hat{\beta}_j]}}$, and then

$$G_n(t, F_n) = \frac{1}{B} \sum_{b=1}^B \mathbf{1}(T_n^{(b)} \leq t)$$

This second option is more accurate than the first one :

Consistency

The approximation error of bootstrap applied to asymptotically pivotal statistic is smaller than the approximation error of bootstrap applied on asymptotically non-pivotal statistic, see Horowitz (1998) [The Bootstrap](#).

Here, asymptotically pivotal means that

$$G_\infty(t, F) = G_\infty(t), \quad \forall F \in \mathcal{F}.$$

Assume now that the quantity of interest is $\theta = \text{Var}[\hat{\beta}]$.

Consider a bootstrap procedure, then one can prove that

$$\begin{aligned} & \text{plim}_{B, n \rightarrow \infty} \left\{ \frac{1}{B} \sum_{b=1}^B \sqrt{n}(\hat{\beta}^{(b)} - \hat{\beta}) \sqrt{n}(\hat{\beta}^{(b)} - \hat{\beta})^\top \right\} \\ &= \text{plim}_{n \rightarrow \infty} \left\{ n(\hat{\beta} - \beta_0)(\hat{\beta} - \beta_0)^\top \right\} \end{aligned}$$

More on Testing Procedures

Consider a sample $\{y_1, \dots, y_n\}$. We want to test some hypothesis H_0 . Consider some test statistic $t(\mathbf{y})$

Idea: t takes large values when H_0 is not satisfied.

The ***p-value*** is $p = \mathbb{P}[T > t_{\text{obs}} | H_0]$.

Bootstrap/simulations can be used to estimate p , by simulation from H_0 .

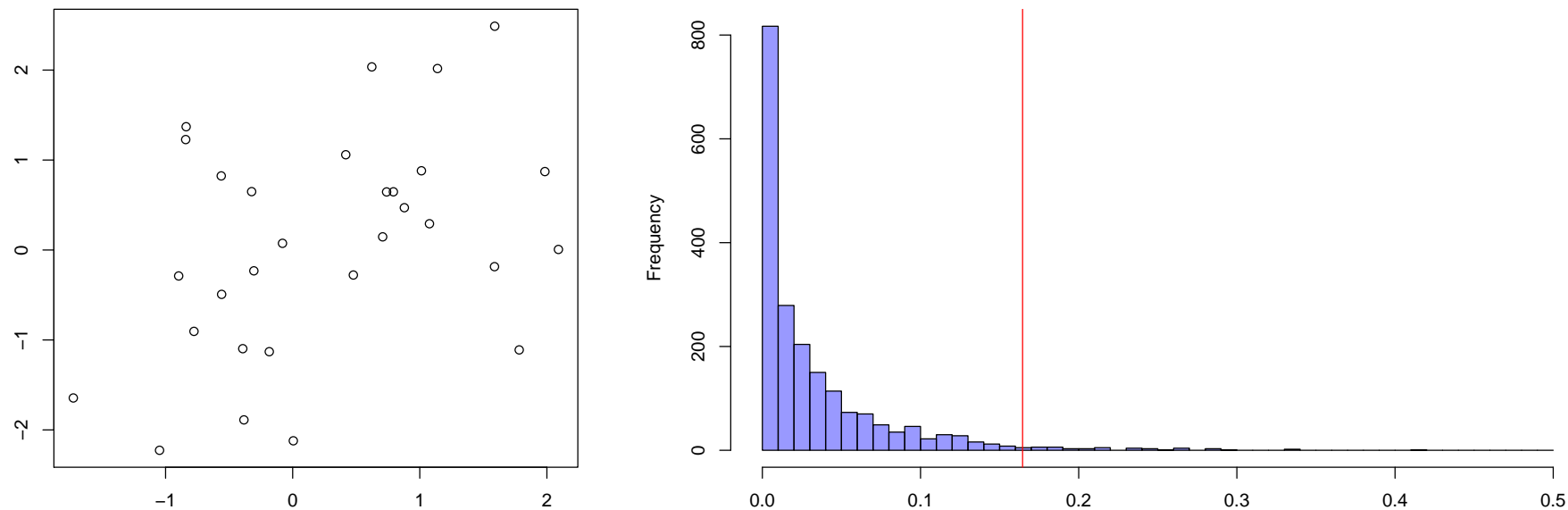
1. Generate $\mathbf{y}^{(s)} = \{y_1^{(s)}, \dots, y_n^{(s)}\}$ generated from H_0 .

2. Compute $t^{(s)} = t(\mathbf{y}^{(s)})$

3. Set $\hat{p} = \frac{1}{1+S} \left(1 + \sum_{s=1}^S \mathbf{1}(t^{(s)} \geq t_{\text{obs}}) \right)$

Example : testing independence, let t denote the square of the correlation coefficient.

Under H_0 variables are independent, so we can bootstrap independently x 's and y 's.



With this bootstrap procedure, we estimate

$$\hat{p} = \mathbb{P}(T \geq t_{\text{obs}} | \hat{H}_0)$$

which is not the same as

$$p = \mathbb{P}(T \geq t_{\text{obs}} | H_0)$$

More on Testing Procedures

In a parametric model, it can be interesting to use a sufficient statistic W . One can prove that

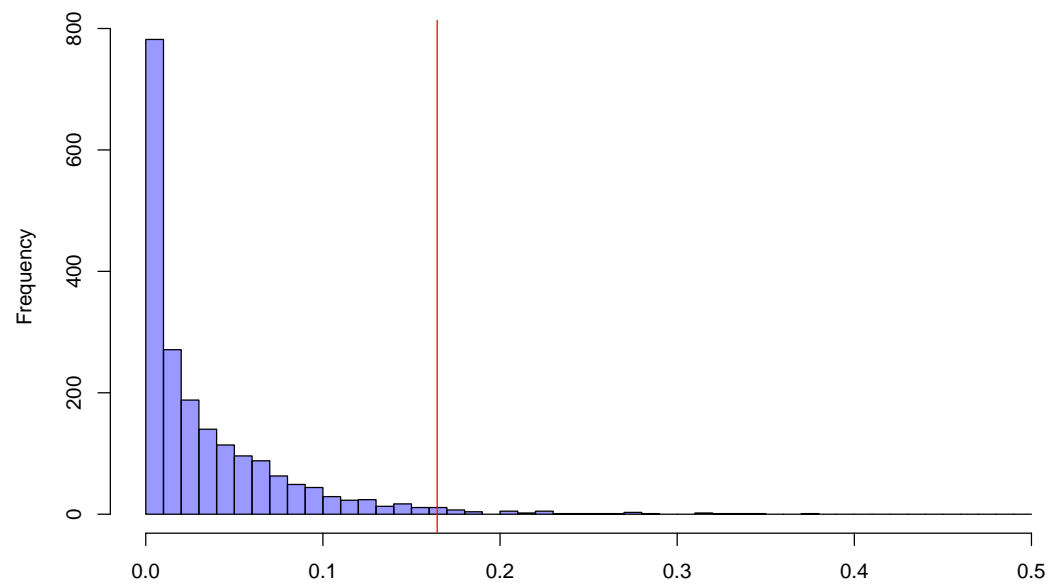
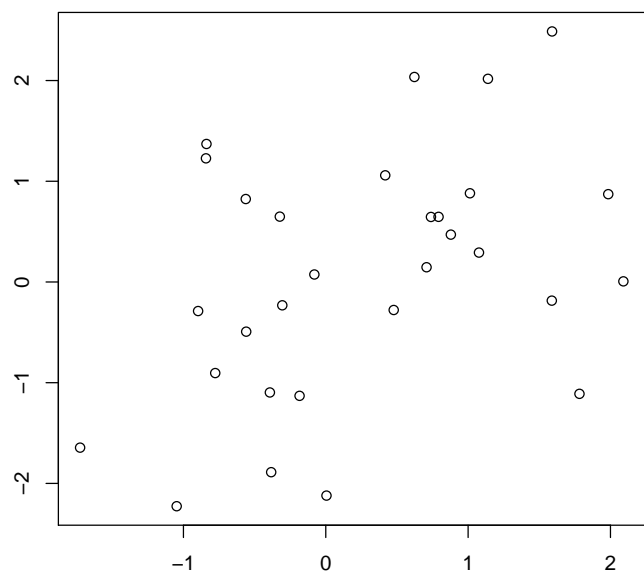
$$p = \mathbb{P}(T \geq t_{\text{obs}} | \hat{H}_0, W)$$

The problem is to generate from this conditional distribution...

Example : for the independence test, we should sample from \hat{F}_x and \hat{F}_y with fixed margins.

Bootstrap should be here **without replacement**.

More on Testing Procedures



More on Testing Procedures

But this nonparametric bootstrap fails when

Gaussian Central Limit Theorem does not apply

Mammen's theorem

Example $X \sim \text{Cauchy}$: limit distribution $G_\infty t, F$ is not continuous, in F

Example : distribution of the maximum of the support (see Bickel and Freedman (1981)): $X \sim \mathcal{U}([0, \theta_0])$

$T_n = n(\theta_n - \theta_0)$ with $\theta_n = \max\{X_1, \dots, X_n\}$

Set $T_n^{(b)} = n(\theta_n^{(b)} - \theta_n)$, and $\theta_n^{(b)} = \max\{X_1^{(b)}, \dots, X_n^{(b)}\}$

Here $T_n \xrightarrow{\mathcal{L}} \mathcal{E}(1)$, exponential distribution, but not $T_n^{(b)}$, since $T_n^{(b)} \geq 0$ (we just resample), and

$$\mathbb{P}[T_n^{(b)} = 0] = 1 - \mathbb{P}[T_n^{(b)} > 0] = 1 - \left(1 - \frac{1}{n}\right)^n \sim 1 - e^{-1}.$$

Resampling or Subsampling ?

Why not draw subsamples of size $m < n$?

- with replacement, see m out of n bootstrap
- without replacement, see subsampling bootstrap

Less accurate than bootstrap when bootstrap works... but might work when bootstrap does not work

Exemple : maximum of the support, $Y_i \sim \mathcal{U}([0, \theta])$,

$$\mathbb{P}_{\hat{F}_n} [T_m^{(b)} = 0] = 1 - \left(1 - \frac{1}{n}\right)^m \sim 1 - e^{-m/n} \sim 0$$

if $m = o(n)$.

From Bootstrap to Bagging

Bagging was introduced in Breiman (1996) **Bagging predictors**

1. sample a bootstrap sample $(y_i^{(b)}, \mathbf{x}_i^{(b)})$ by resampling pairs
2. estimate a model $\hat{m}^{(b)}(\cdot)$

The bagged estimate for m is then $m_{\text{bag}}(\mathbf{x}) = \frac{1}{B} \sum_{b=1}^B \hat{m}^{(b)}(\mathbf{x})$

From Bagging to Random Forests